





# Intelligent Low Voltage Solid State Motor Control Products

with next generation MX<sup>2</sup>/MX<sup>3</sup> technology

# MX<sup>2</sup> Control Technology

Next Generation Intelligent Motor Control

#### Next Generation Intelligent Motor Control

- Mission critical reliability
- Patented soft start technology
- Integral digital protection and metering
- Continuous and integral bypass chassis
- RXE redundant configurations
- MXP modular, prepackaged starters
- Reversing, two-speed, wound rotor
- Synchronous, dc injection braking
- 24/7 service and support



**Optional Keypad** 



#### MX<sup>2</sup> Control Highlights

The MX<sup>2</sup> control technology from Benshaw provides a powerful, flexible, intelligent low voltage motor control platform. MX<sup>2</sup>-based controls offer multiple, user selectable starting modes, an increased selection of configurable digital and analog I/O's, comprehensive built-in metering capabilities, unprecedented onboard protection and an easy to use, intuitive user interface.

Our control board terminal configuration—coupled with programmable burden CT settings—makes Benshaw's MX<sup>2</sup> technology an excellent choice for a wide range of intelligent, soft start motor control applications.

Benshaw's MX<sup>2</sup>-based low voltage motor controls raise the bar for intelligent, low-cost, soft start motor control.

When you factor in our unique three-year factory warranty and 24/7 comprehensive technical support, we think you'll find Benshaw's MX<sup>2</sup>-based controls to be an excellent value.

#### Standard Features:

- High performance motor control with multiple starting modes built in
- Jogging 7 and 14% speed
- 3 user configurable digital inputs
- 2 fixed inputs for start and bypass confirm
- 3 user configurable output relays and 1 fixed bypass confirm
- User configurable analog I/O
- Programmable burden CT settings
- Residual ground fault
- Advanced line / motor metering
- DC braking light duty

- Power stack thermistor
- Data snapshot of each fault
- Power up on start
- 1,000 V capable
- Energy saver
- Remote keypad ready
- UL, CUL, NEMA compliance
- Built-in self-testing (BIST)
- Modbus 485 plus expanded communications capabilities with optional MXDE3 communications module



## MX<sup>2</sup> Control Features

#### Multiple Starting Modes:

- Voltage ramp
- Current ramp
  - Adjustable initial current
  - Adjustable maximum current
  - Adjustable ramp time
- Torque ramp (TruTorque<sup>™</sup>)
  - Adjustable initial torque
  - Adjustable maximum torque
  - Adjustable ramp time

#### **Motor Protection:**

- Motor thermal overload
- Independent starting and running OL's
- Up to speed timer
  exceeded
- Low line voltage
- Low line frequency
- Metering:
- ± 2% accuracy
- Average current
- L1 current
- L2 current
- L3 current
- Current
  imbalance %
- Ground fault amps/ residual
- Average volts
- L1–L2 voltage

- Power ramp
  - Adjustable initial torque
  - Adjustable maximum torque
  - Adjustable ramp time
- Linear/tach feedback control
- Jogging 7 and 14% speed

- 3 Relay Outputs Configurable to:
- Starter off
- Faulted fail safe and non fail safe
- Running
- Up to speed
- Alarm condition
- Ready condition
- Locked out
- Overcurrent trip
- Undercurrent trip

- OL alarm
- Shunt trip fail safe and non fail safe
- Ground fault
- Energy saver indication
- Heating indication
- Slow speed forward/reverse
- DC braking
- Cooling fan
- 1 fixed bypass

• Trip low level

#### 1 Analog 4 – 20 mA /0 – 10 Vdc Input Configurable to:

Trip high level

#### 1 Analog 4 – 20 mA / 0 – 10 Vdc Output Configurable to:

- Current (0-200%/0-800%)
- Voltage (0–150%)
- OL (0-150%)
- •
- KW (0-10 KW/0-100 KW)
- Firing (0-100%)Calibration

starter

• Ethernet/IP

Modbus TCP

MW (0-1 MW)

Analog input (0-100%)

View status information

frequency in real time

View line current, voltage and

- Start and stop the solid state

- KVV (U-10 KVV/U-100 KVV
- User Interface:
- Standard board-mounted LED interface
- Optional remote mount LCD display
  - Set/examine operating parameters

#### **1 Communication Port Included:**

• Modbus RTU / RS485

#### Optional with MXDE3:

- DeviceNet
- Ethernet

#### Advanced Functionality:

- Dual ramp selectionAdjustable kick current
- Programmable decel modes
- LV BIST test (built-in self test)

OL resetLocal/remote

3 Digital Inputs Configurable to:

Fault reset

Stop

Fault

•

- Bypass/confirmation & inline
- selectionHeater enable
- Heater disable
- Dual ramp selection
  - 1 dedicated start input
    - 1 dedicated bypass

## Ground fault residualShorted SCR

- Disconnect fault
- Inline contactor fault
- Control power low
- Stack over
  temperature

## \_\_\_\_\_

Analog input

#### Analog output

- Run time days
- Run time hours
- # of starts
- TruTorque<sup>™</sup> %
- Power %

#### Peak starting current

 Last starting duration

L2–L3 voltageL3–L1 voltage

High line frequency

Phase reversal

Phase loss

Instantaneous

overcurrent

Overcurrent

Undercurrent

Overload %

Power factor

Watts

VARS

KW hours

MW hours

Phase order

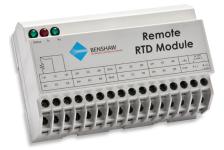
Line frequency

\/A

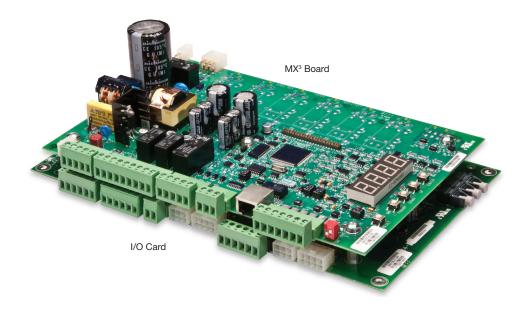
Current imbalance

# MX<sup>3</sup> Control Technology

Next Generation Intelligent Motor Control



Optional RTD modules



#### BENSHAW BUCH DE LA LARA DE LA LARA TOLE DE LAR

Keypad (Included)

#### MX<sup>3</sup> Control Highlights

Benshaw's next generation MX<sup>3</sup> technology propels low voltage motor control to even greater levels of performance and functionality. With its real-time clock, enhanced programming capabilities, ease of use and a unique, flexible architecture—Benshaw's MX<sup>3</sup> controller delivers advanced motor control and protection with all of the rugged, dependable performance you've come to expect from a world leader in advanced controls and drives.

MX<sup>3</sup> controllers, power components, software and sensors are all designed, built and tested to perform as an integrated control system, eliminating the coordination and performance problems inherent in other forms of reduced voltage starting.

Benshaw's next generation MX<sup>3</sup> technology will shorten your commissioning times, improve motor performance and protection, enhance diagnostic capability and streamline electrical system monitoring and maintenance tasks.

#### Benshaw's MX<sup>3</sup> control technology provides all MX<sup>2</sup> features, plus:

- 8 user configurable inputs
- 2 fixed inputs for start and bypass confirm
- 6 user configurable relay outputs
- 1 fixed output for bypass confirm
- Real-time clock
- Motor PTC input
- Zero Sequence Ground Fault
- RTD module support
- Full DC braking with add-on SCR
- Event log (99 events)

- Start per hour limiter
- Back spin timer
- Time between starts limiter
- · Zero speed switch input
- Power outage ride through (PORT)
- Power factor trip
- Patented Cyclo<sup>™</sup> control (0-40% speed)



## MX<sup>3</sup> Control Features

#### **Multiple Starting Modes:**

- Voltage ramp
- Current ramp
  - Adjustable initial current
  - Adjustable maximum current
  - Adjustable ramp time
- Torque ramp (TruTorque<sup>™</sup>)
  - Adjustable initial torque
  - Adjustable maximum torque

#### Motor Protection:

- Motor thermal overload
- Independent starting and running OL's
- Up to speed timer exceeded
- Low line voltage
- Low line frequency
- High line frequency
- Metering:
- ± 2% accuracy
- Average current
- L1 current
- L2 current
- L3 current
- Current imbalance %
- Ground fault amps/ residual
- Average volts
- L1–L2 voltage
- L2–L3 voltage
- 6 Digital Inputs Configurable to:
- Stop
- Fault
- Fault reset
- Bypass/confirmation & inline

- Phase reversal Phase loss
- Instantaneous
- overcurrent Overcurrent
- Undercurrent
- Current imbalance
- Shorted SCR
- Disconnect fault
- L3–L1 voltage Analog output

- Adjustable ramp time

- Adjustable initial torque

- Adjustable ramp time

Cyclo<sup>™</sup> converter control

Linear/tach feedback control

Adjustable maximum torque

Ground fault

sequence)

Stack over

temperature

RTD modules

TruTorque<sup>™</sup> %

Peak starting

Last starting

Real-time clock

duration

Power %

current

Motor PTC input

(residual or zero

Inline contactor fault

Control power low

Power ramp

- Overload %
- Power factor
- Watts
- VA
- VARS
- KW hours
- MW hours
- Phase order
- Line frequency
- Analog input

OL reset

Local/remote

Heater enable

Heater disable

selection

- - Dual ramp selection 1 dedicated start
  - input 1 dedicated bypass

#### 6 Relay Outputs Configurable to:

- Starter off
- Faulted fail safe and non fail safe
- Running
- Up to speed
- Alarm condition
  - Ready condition

- Locked out
- Overcurrent trip
- Undercurrent trip
- OL alarm
- Shunt trip fail safe and non fail safe
- Ground fault
- DC braking Cooling fan

reverse

 Energy saver indication

Heating indication

Slow speed forward/

1 fixed bypass

#### 1 Analog 4 – 20 mA / 0 – 10 Vdc Input Configurable to:

 Trip high level Trip low level

#### 1 Analog 4 – 20 mA / 0 – 10 Vdc Output Configurable to:

MW (0-1 MW)

Firing (0-100%)

Calibration

Analog input (0-100%)

View status information

frequency in real time

- View line current, voltage and

- Start and stop the solid state

- Current (0-200%/0-800%)
- Voltage (0-150%)
- OL (0-150%)
- KW (0-10 KW/0-100 KW)

#### **User Interface:**

- LED interface
- Optional remote mount LCD display
  - Set/examine operating parameters

#### 1 Communication Port Included:

Modbus RTU / RS485

#### **Optional with MXDE3:**

DeviceNet

 Ethernet/IP Modbus TCP

starter

• Ethernet

#### Advanced Functionality:

- Dual ramp selection
- Adjustable kick current
- Programmable decel modes
- LV BIST test (built-in self test)
- Event log (99 events)

- Run time days Run time — hours # of starts
- Standard board-mounted

# **Control Feature Comparison**

| Function:   | MX <sup>2</sup> | MX <sup>3</sup> |
|---|-----------------|-----------------|
| Soft Starting and Stopping                          |                 |                 |
| Voltage Ramp  | √               | $\checkmark$    |
| Current Ramp  | $\checkmark$    | $\checkmark$    |
| TruTorque <sup>™</sup> Ramp                         | $\checkmark$    | $\checkmark$    |
| Power Ramp  | $\checkmark$    | $\checkmark$    |
| Tach/Speed Control Ramp                             |                 | $\checkmark$    |
| Linear Ramp Profiles                                | $\checkmark$    | $\checkmark$    |
| Squared and S Ramp Profiles                         |                 | $\checkmark$    |
| Dual Ramps  | $\checkmark$    | $\checkmark$    |
| Kicking   | $\checkmark$    | $\checkmark$    |
| Voltage Decel                                       | $\checkmark$    | $\checkmark$    |
| TruTorque <sup>™</sup> Decel                        | $\checkmark$    | $\checkmark$    |
| DC Braking  | $\checkmark$    | $\checkmark$    |
| Heater/Antiwindmill                                 | $\checkmark$    | $\checkmark$    |
| Jogging 7–14% Speed                                 | $\checkmark$    | $\checkmark$    |
| Slow Speed Cyclo <sup>™</sup> Operation 0–40% speed | $\checkmark$    | $\checkmark$    |
| Inside Delta  | $\checkmark$    | $\checkmark$    |
| Wye-Delta/Electromechanical Control                 | $\checkmark$    | $\checkmark$    |
| Phase Controller                                    | $\checkmark$    | $\checkmark$    |
| Current Follower                                    | $\checkmark$    | $\checkmark$    |
| ATL   | √               | $\checkmark$    |

| Function:                                  | MX <sup>2</sup> | MX <sup>3</sup> |
|--|-----------------|-----------------|
| Protection                                 |                 |                 |
| Separate Starting/Running Overload Classes | $\checkmark$    | $\checkmark$    |
| Adj. Hot/Cold Ratio                        | $\checkmark$    | $\checkmark$    |
| Adj. Cooling Time                          | ✓               | $\checkmark$    |
| Intelligent Start Lockout                  |                 | $\checkmark$    |
| Adj. OL Lockout Level                      |                 | $\checkmark$    |
| Over/Undercurrent Protection               | $\checkmark$    | $\checkmark$    |
| Retained OL When Power Lost                | $\checkmark$    | $\checkmark$    |
| Current Imbalance Protection               | $\checkmark$    | $\checkmark$    |
| IOC (Instantaneous Overcurrent)            | $\checkmark$    | $\checkmark$    |
| Open/Shorted SCR Detection                 | $\checkmark$    | $\checkmark$    |
| Overcurrent/Shear Pin                      | $\checkmark$    | $\checkmark$    |
| Undercurrent/Load Loss                     | $\checkmark$    | $\checkmark$    |
| Residual Ground Fault Protection           | $\checkmark$    | $\checkmark$    |
| Zero Sequence Ground Fault Protection      |                 | $\checkmark$    |
| Starts Per Hour                            |                 | $\checkmark$    |
| RTD Monitoring                             |                 | $\checkmark$    |
| Motor PTC                                  |                 | $\checkmark$    |
| Stack OT Switch                            | $\checkmark$    | $\checkmark$    |
| Stack Thermistor Input                     | $\checkmark$    | $\checkmark$    |
| Backspin Timer                             |                 | $\checkmark$    |
| Time Between Starts                        |                 | $\checkmark$    |
| Phase Rotation                             | $\checkmark$    | $\checkmark$    |
| Overvoltage                                | $\checkmark$    | $\checkmark$    |
| Undervoltage                               | $\checkmark$    | $\checkmark$    |
| Phase Loss                                 | $\checkmark$    | $\checkmark$    |
| UTS/Stall Timer                            | $\checkmark$    | $\checkmark$    |
| Zero Speed Switch                          |                 | $\checkmark$    |
| PF Trip                                    |                 | $\checkmark$    |
| PORT (Power Outage Ride Through)           |                 | $\checkmark$    |
| Keypad Fault Reset                         | $\checkmark$    | $\checkmark$    |
| Adj. Auto Fault Reset Timer                | ✓               | $\checkmark$    |
| Adj. No. of Auto Resets Before Lockout     | $\checkmark$    | $\checkmark$    |
| Decel After Fault                          | $\checkmark$    | $\checkmark$    |
| Fault Log                                  | $\checkmark$    | $\checkmark$    |
| Time and Date Stamp                        |                 | $\checkmark$    |
| 9 Data Snapshots of Each Fault             | $\checkmark$    | $\checkmark$    |
| Event Log (last 99 events)                 |                 | √               |
| Fault Classes                              |                 |                 |
|  |                 |                 |



| Function:                                  | MX <sup>2</sup> | MX <sup>3</sup> |
|--|-----------------|-----------------|
| Metering                                   |                 |                 |
| Full Voltage and Current Metering          | ~               | $\checkmark$    |
| True RMS Calculation                       | $\checkmark$    | $\checkmark$    |
| Factory Menu Calibration                   | $\checkmark$    | $\checkmark$    |
| Current Imbalance Meter                    | $\checkmark$    | $\checkmark$    |
| Ground Fault Meter                         | $\checkmark$    | $\checkmark$    |
| Watt Meters                                | $\checkmark$    | $\checkmark$    |
| KVA Meters                                 | $\checkmark$    | $\checkmark$    |
| VAR Meter                                  | $\checkmark$    | $\checkmark$    |
| Watt Hour Meters                           | $\checkmark$    | $\checkmark$    |
| Line Frequency Meter                       | $\checkmark$    | $\checkmark$    |
| Power Factor Meter                         | $\checkmark$    | $\checkmark$    |
| % OL Meter                                 | $\checkmark$    | $\checkmark$    |
| Time Until OL Lockout Release Meter        | $\checkmark$    | $\checkmark$    |
| Phase Rotation Meter                       | $\checkmark$    | $\checkmark$    |
| & Power and % TruTorque <sup>™</sup> Meter | $\checkmark$    | √               |
| Run Time Meter                             | $\checkmark$    | $\checkmark$    |
| Number of Starts Meter                     | $\checkmark$    | √               |
| Peak Current of Last Start Meter           | $\checkmark$    | $\checkmark$    |
| Last Starting Time Meter                   | $\checkmark$    | √               |
| Analog Input Meter                         | $\checkmark$    | $\checkmark$    |
| Real-Time Clock                            |                 | √               |
| RTD Meters                                 |                 | ✓               |

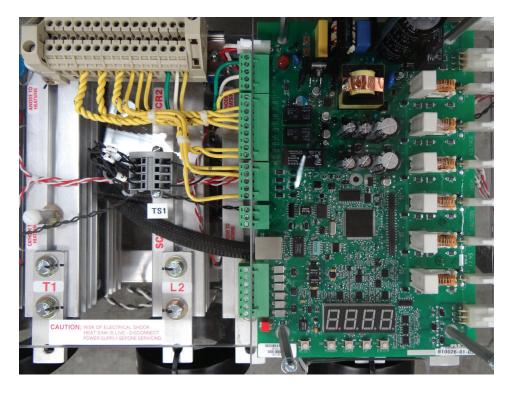
| Function:                       | MX <sup>2</sup> | MX <sup>3</sup> |
|---------------------------------|-----------------|-----------------|
| User I/O                        |                 |                 |
| Programmable Digital Inputs     | $\checkmark$    | $\checkmark$    |
| Programmable Digital Outputs    | ✓               | $\checkmark$    |
| User Analog Input               | ✓               | $\checkmark$    |
| Programmable User Analog Output | $\checkmark$    | $\checkmark$    |
| Local/Remote Source Input       | $\checkmark$    | $\checkmark$    |
| Power Up Start                  | $\checkmark$    | $\checkmark$    |
|                                 |                 |                 |
| Function:                       | MX <sup>2</sup> | MX <sup>3</sup> |
| Miscellaneous                   |                 |                 |
| LV BIST                         | ✓               | $\checkmark$    |
| MV BIST                         | $\checkmark$    | $\checkmark$    |
| LV Powered BIST                 | $\checkmark$    | $\checkmark$    |

## Open Chassis Starters Non-Bypassed/Continuous Duty



RC Series MX<sup>2</sup> or MX<sup>3</sup> Technology

Rugged Industrial Solid State Starters 1–1200 HP / 208–600 Vac



#### **RC Series Product Highlights**

The RC Series Solid State Starter combines the high performance  $MX^2$  or  $MX^3$  control with the rugged, continuous duty, fan cooled RC stack.

The MX<sup>2</sup> or MX<sup>3</sup> series control provides users with a powerful group of programming parameters, designed for flexibility in industrial applications. The MX<sup>2</sup> and MX<sup>3</sup> both provide simple setup and commissioning via the Quick Start Menu.

The RC power section is a rugged non-bypassed section. It is an economical solution at low horse-power. In addition, the fan cooled stack provides high duty cycle and high inertia starting and energy saver operation.

- Economical at low horsepower
- High duty cycle starting
- Long starting times
- Suitable for jogging applications
- Fan cooled stack
- Energy saver applications
- Integrated motor protection

- Modbus standard / Profibus, Ethernet, DeviceNet, Ethernet IP web addressable communication protocols are available via optional communication bridges
- 1.25 service factor
- Integrated metering and diagnostics
- Multiple starting ramps for various applications



Integral Bypass Contactor

# **Open Chassis Starters** with Integral Bypass

RB Series with MX<sup>2</sup> Technology (also available with MX<sup>3</sup> Technology)

### **RB Series Product Highlights**

Benshaw's RB series solid state starter combines the high performance MX<sup>2</sup> or MX<sup>3</sup> technology with a rugged, compact, integral bypass RB series power section.

The MX<sup>2</sup> or MX<sup>3</sup> technology provides users with a powerful group of programming parameters, designed for flexibility in across a wide range of industrial applications. Both MX<sup>2</sup> and MX<sup>3</sup> controls provide simple setup and commissioning via the Quick Start Menu.

The RB power section is a rugged, heavy duty solid state starter section designed with integral bypass contactors for a compact, efficient profile. The modular design includes separate poles for each phase for ease of maintenance.

## **Key Advantages**

- · Small, compact design
- Modular power stack assembly for ease of maintenance
- Modbus standard / other Fieldbus optional
- Multiple starting ramps for various applications

RB Power Pole—180 A

- Integrated metering system diagnostics
- Integral bypass contactors for efficient operation, eliminating the need for external fans
- Integrated motor protection
- Dual ramp capability for loaded / unloaded applications
- · Power stack has multiple ratings for application flexibility

#### **Rugged Industrial Solid State Starters with Integral Bypass**







## Prepackaged Starters with ATL Bypass Severe Duty 480V



MX<sup>2</sup> / MX<sup>3</sup> RX2E Series or RX3E

NEMA 12 / Combination / Redundant





#### **RX2E Series Product Highlights**

RX2E starters provide solid state reduced voltage starting for normal operation and full voltage emergency backup starting with complete electronic motor protection at the flip of a switch. This unique redundant design is the ideal solution for critical applications where downtime is extremely disruptive to production operations and cannot be tolerated. Benshaw's MX solid state controls provide precise digital starting and stopping, motor protection, metering, diagnostics and communications.

Units are stocked with MX<sup>2</sup> technology, but are also available with MX3 technology.

#### **Standard Features**

- NEMA 12, redundant, combination/ circuit breaker
- Shunt trip on main circuit breaker
- 500%-30 seconds rated solid state starter, UL certified and listed
- 1800 PIV rated SCRs, UL certified and listed
- 125% continuous duty rated solid state starter, UL certified and listed
- Selector switch for selecting solid state or full voltage operation mounted inside enclosure
- Full HP rated bypass contactor with a 1.15 service factor, wired for normal bypass operation and full voltage start and run operation, with normally open auxiliary contact
- Separately mounted "SPE" series overload relay wired for full voltage start and run operation
- 110 volt control power transformer with primary and secondary fuses

- Door mounted start and stop pushbuttons
- Door mounted keypad
- Door mounted run indicating light
- Door mounted local-off remote switch
- Door mounted overload reset
- Terminal strip mounted inside enclosure for remote start/stop connection
- Auxiliary relay with (2) Form C run contacts
- Benshaw MX<sup>2</sup> programmable motor controller with soft start, soft stop and motor protection capabilities
- RS485 Modbus communications
- Analog I/O
- Available with MX<sup>3</sup> technology
- Optional NEMA 4 enclosure



# Prepackaged Starters Non-Bypassed / Continuous Duty and Integral Bypass

MX<sup>2</sup>PB / MX<sup>2</sup>PC Series

Prepackaged Starters with MX2 Technology. Modified for Next Day Shipment.

#### Configure the MX<sup>2</sup>PB/MX<sup>2</sup>PC to fit your application

#### **Standard Features**

- Non-combination
- Combination circuit breaker
- Rotary disconnect operator
- Non-bypass
- Bypass contactor
- NEMA 4 or 12 enclosure

- Modular operator station
- 480 V
- Standard 120 V control
  power transformer
- Service entrance rated
  with circuit breaker



- 1. Select a starter type:
  - MX<sup>2</sup>PC modular non-bypass or
  - MX<sup>2</sup>PB modular bypass

- 2. Select a horsepower rating
- 3. Select a voltage
- 4. Select an enclosure

- 5. Select a circuit breaker (or none)
- 6. Select your options











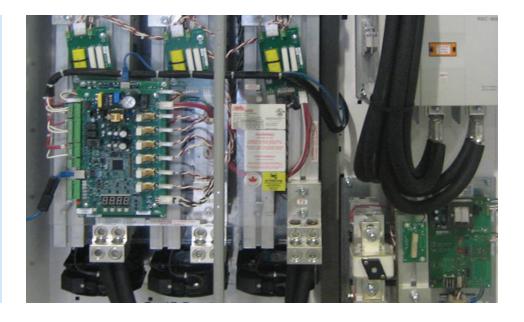
(Stock Unit Shown)

# **RB2/RB3** Series Starter with DC Injection Brake

Solid State Starter with DC Injection Control

#### **Ratings:**

| Horsepower:      | 20-1,500 HP                            |
|------------------|--|
| Overload:        | 500% for 30 seconds<br>125% continuous |
| Starting Torque: | 0–100%                                 |
| Voltage:         | 200–1,000 Vac                          |
| Standard Duty:   | 300% braking current for 30 seconds    |
| Heavy Duty:      | 300% braking current for 60 seconds    |



#### **DC Injection Braking Starter Product Highlights**

Benshaw offers a microprocessor controlled solid state reduced voltage starter with dc injection braking for three-phase induction motors. The starter provides a closed loop current ramp for smooth stepless motor acceleration.

The  $MX^2$  /  $MX^3$  starter with dc injection brake consists of the Benshaw three-phase SCR power stack for the soft start, with an integrated SCR power block power fuse and control logic for the dc injection circuit.

The  $MX^2$  /  $MX^3$  dc injection brake SCR system allows a free wheeling path for the dc current that circulates in the motor windings. When the dc current is applied to the ac motor windings, braking action is achieved as the circulating motor rotor tries to align itself with the stationary dc field, thus giving the motor smooth electronic braking action.

- Benshaw MX<sup>2</sup> / MX<sup>3</sup> technology
- Standard and heavy duty dc injection brake configurations available
- Modular power stack design for ease
  of maintenance
- Solid state starter and dc brake integrated in one package
- Integral bypass contactor design
- Advanced MX<sup>2</sup> / MX<sup>3</sup> motor protection

- Advanced MX<sup>2</sup> / MX<sup>3</sup> metering function
- Real-time clock
- 99 event log history
- Modbus communication
- Configurable output relays
- Reduced maintenance
- Reversing capabilities are also available



## Synchronous Starter

MX2 SEP Series—Solid State Starter with Synchronous Control



#### Synchronous Starter Product Highlights

The sync motor functions as an induction motor during start up. Once the motor approaches full synchronous speed, the  $MX^2 / MX^3$  dc exciter induces a constant polarity to the rotor, causing the motor to lock into sync. Because the rotor's field is constant and separately excited, there is no slip required to produce torque, as with an induction motor. This allows the motor to run at synchronous speed.

The Benshaw synchronous package consists of a solid state starter portion connected to the stator and an SEP (synchronous excitation package) that is connected to the rotor section in conjunction with a discharge resistor. This SEP is supplied for brush type and brushless exciters.

#### Synchronous Benefits

The MX<sup>2</sup> / MX<sup>3</sup> series solid state starter provides reduced voltage stepless acceleration and automatic synchronization of three-phase ac synchronous motors. Synchronous motors are utilized for a number of reasons. They are used in applications that require precise motor speed. They are used to obtain greater efficiencies, and they are used for facility power factor correction.

Since synchronous motors can be operated at leading power factor, they are used to correct a facility's lagging power factor created by all the other induction motors being operated.

This correction reduces the penalty a customer pays the utility company for creating poor power factor.

Synchronous motors are not sensitive to electrical harmonic problems.

| Ratings  |  |
|--|--|
| Horsepower:  | 20-1,500 HP                            |
| Overload:  | 500% for 30 seconds<br>125% continuous |
| Starting Torque:   | 0–100%                                 |
| Voltage:   | 200–1,000 Vac                          |
| Includes discharge resistor and<br>synchronous excitation package<br>for brush type and brushless motor. |  |
| Exciter<br>Ratings:  | 125–250 Vdc<br>30–300 A                |

- Benshaw synchronous technology
- Solid state synchronous rotor control
- Modular power stack design for ease of maintenance
- Integral bypass contactor design
- Advanced synchronous motor protection
- Can be added to existing equipment
- Can be supplied with MX<sup>2</sup> or MX<sup>3</sup> starter control
- Modbus communication
- Configurable output relays
- Reduced maintenance
- Reduction in size compared to existing field control
- Stepless control
- Reduces inrush while maintaining torque
- Brush type and brushless control

## Wound Rotor Starter

With MX<sup>3</sup> Technology— Solid State Starter with Wound Rotor Control

#### **Ratings:**

| Horsepower:                  | 20-1,500 HP                            |
|------------------------------|--|
| Overload:                    | 500% for 30 seconds<br>125% continuous |
| Starting Torque:             | 0–100%                                 |
| Voltage:                     | 200–1,000 Vac                          |
| Typical<br>Resistance Steps: | 1–2                                    |



#### Wound Rotor Starter Product Highlights

Wound rotor motors are typically used in applications requiring high starting torques, a limited number of operating speeds or a stepped acceleration to achieve a soft start. Typical existing applications utilize an electromechanical starter on the stator and introduce multiple stages of resistance in the rotor via contactor arrangements to achieve a soft ramp.

With the MX<sup>3</sup> technology, wound rotor control is greatly simplified. The MX<sup>3</sup> technology consists of two major sections: 1) a solid-state stator control, and 2) a single step of resistance into the rotor circuit from a separate three-phase resistor bank. This achieves the high torque required by the application—with low inrush while providing a smooth stepless start. This greatly reduces the maintenance cost of the typical electromechanical control.

#### Single Step Rotor Control

The solid-state starter is wired to the motor stator circuit, and the resistor and shorting contactor are wired to the motor rotor circuit. The solid state starter accelerates the motor to slip speed (determined by the resistance value) and then activates the contactor to short the rotor. This allows the motor to accelerate to full speed.

#### **Multiple Step Rotor Circuit**

RBW series starters can be supplied with multiple stages of rotor resistor and contactor combinations. This arrangement may be necessary for multiple step starting of extremely high inertia loads, or for continuous operation at multiple speeds. Multiple steps of rotor resistance can be coordinated to achieve this.

#### Variable Speed Control

Variable speed control of wound rotor motors can be accomplished with the MX<sup>3</sup> technology series control. By maintaining full output voltage of the control going to the stator of the wound rotor motor, and varying the resistance in the rotor, variable speed is accomplished.

Resistors must be rated for continuous duty operations. Variable loads (pumps and fans) only.

- Benshaw MX<sup>3</sup> technology
- Single step rotor control
- Modular power stack design for ease of maintenance
- Integral bypass contactor design
- Advanced MX<sup>3</sup> motor protection
- Advanced MX<sup>3</sup> metering function
- Real-time clock
- 99 event log history
- Modbus capable
- Configurable output relays
- Multistep and variable speed rotor control available
- Reduced maintenance
- Reduced in size and number of resistors needed
- Stepless control
- Reduces inrush while maintaining torque



# **Engineered Packages**

#### **Product Overview**

Benshaw has developed advanced engineering, drafting, materials management and quality systems focused on designing and building customer solutions. This "Build to Order" capability combined with an extensive inventory of control components, protective relays, circuit breakers, contactors, enclosures and other electrical / electronic devices enables Benshaw to quickly ship engineered products.

#### Control Modifications—Whatever You Specify

 Over 250 modifications and accessories are available, including: pilot devices, PLCs, control power transformers, switches, meters, relays, space heaters and protective devices.

#### Combination Starters—to Meet Your Requirements

- 15 to 2,000 A circuit breakers
- 40 to 2,000 A non-fused disconnects
- 30 to 800 A fusible disconnects
- Flange or rotary handle mechanism

#### Power Stacks—to Fit Your Application

- Continuous duty / non-bypassed
- Integral bypass
- Standard, heavy and severe duty
- Emergency across-the-line bypass

#### Enclosures—to Match Your Environment

- Standard designs NEMA 1, 12, 4 chassis
- Custom enclosures
- Special enclosures NEMA 3R, 4X, 7, 9, as specified
- Motor control centers

#### Communication

• Modbus / RS485





#### **Advanced Controls and Drives**

Full Voltage Controls

Variable Frequency Drives

Low Voltage Solid State Starters

Medium Voltage Drives

Medium Voltage Controls

Medium Voltage Switchgear

#### UNICO Technologies Group Power and Precision in Motion

Taking care of our customers' power needs has been our single focus for 88 years. Our two leading brands bring innovative control and electrical solutions to solve your challenges. Through thousands of systems in a broad array of applications, we've learned what it takes to make your system live up to its potential.

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We bring you mission-critical motor control and protection products, designed and built with expertise and precision to maximize your output and minimize downtime.

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#### 24/7 Technical Support

- 24/7 hotline support from Pittsburgh (USA) and Listowel (Canada)
- Overnight parts shipment
- Coordination of all service capabilities repair, spare parts, field engineering, retrofit and training

#### Repairs

- Trained, experienced, field personnel
- Equipped with the latest diagnostic and test equipment
- Start-up commissioning, field repairs, field analysis/data collection and preventative maintenance

#### **Benshaw Product Line**

- Solid state starters fractional to 30,000 HP at 15 kV
- LV AC drives to 700 HP
- MV AC drives to 12,000 HP
- Electromechanical controls to 800 A

#### **Benshaw Express**

- 24/7 online inventory and order system for authorized Benshaw distributors
- 24/7 shipment
- Air or truck delivery

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